Almas Shintemirov

Curriculum Vitae (updated 10/2021)

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PERSONAL INFORMATION

Nationality: Kazakhstan

Languages: Russian (native), English (fluent), Kazakh (intermediate)

EXPERIENCE

Sept. 2019 – present	**Acting Chair,** Department of Electrical and Computer Engineering Nazarbayev University, Kazakhstan
Aug. 2011 – present	**Associate Professor,** Department of Robotics and Mechatronics, Nazarbayev University, Kazakhstan (2011-2015 – Assistant Professor)
Dec. 2009 – Aug. 2011	**Senior Researcher,** Department of Intellectual Systems and Energy Efficiency (since 2011), PI "Nazarbayev University Research and Innovation System" (NURIS) **Senior Manager,** Directorate for Scientific and Technical Projects (until Aug. 2010 – Department for Academic Development), JSC "Nazarbayev University", Kazakhstan
Oct. 2005 – June 2009	**Graduate Teaching Assistant (part-time),** Department of Electrical Engineering and Electronics, the University of Liverpool, U.K.
Mar. 2004 – July 2005	**Instructor,** Department of Electric Power Engineering, S. Toraighyrov Pavlodar State University, Kazakhstan

EDUCATION

2005 – 2009	**Ph.D. in Electrical Engineering and Electronics**, The University of Liverpool, the United Kingdom
2001 – 2004	**Candidate's (Ph.D) Degree in Technical Sciences** (Electrotechnical Complexes and Systems), S. Toraighyrov Pavlodar State University, Kazakhstan
1996 – 2001	**Engineer's Specialist Diploma with Honours (**Electric Drives and Automation of Technological Complexes (equivalent to German Dipl.-Ing. degree), S. Toraighyrov Pavlodar State University, Kazakhstan

CURRENT RESEARCH INTERESTS

Information on research activities with video demos is available at https://www.alaris.kz

- Motion planning of autonomous mobile robots
- Robot-manipulator control for intelligent automation and assistive robotics applications
- Spherical parallel manipulator based mechanisms design and control
- Wearable and rehabilitation robotic system design and analysis
- Computation intelligence for system identification, condition monitoring and decisions making

FUNDED RESEARCH AND INDUSTRIAL PROJECTS

2022 – 2024   **Principal investigator:** "Development of Shared Autonomy Human–Machine Control Interfaces for Intelligent Wheelchair Mounted Robot Arm Systems" (414,000 USD).
- The project proposal was peer-reviewed through ORAU (http://www.orau.org) and approved to be funded from 2022 through the Collaborative Research Grant program by Nazarbayev University.

2021 – 2023   **Principal investigator:** "Development of a Multipurpose Autonomous Hospital Mobile Robot-Manipulation Platform" (Project #021220FD1751, 150,000 USD).
- The project proposal was peer-reviewed through ORAU (http://www.orau.org) and is being funded through the Faculty Development Competitive Research Grant program by Nazarbayev University.

2020 – 2022   **Principal investigator:** "Development of an Autonomous Skid-Steering Based Mobile Robot-Manipulation System for Automating Warehouse Operations in Kazakhstan" (Project IRN AP08052091, 135,530 USD)
- Research project grant from the Kazakhstan Ministry of Education and Science.

2020 – 2022   **Co-Principal investigator:** "Stochastic and Learning-Based Predictive Control Methods for Physical Human-Robot Interaction" (Project #091019CRP2118, 382,920 USD).
- The project proposal was peer-reviewed through ORAU (http://www.orau.org) and is being funded through the Collaborative Research Grant program by Nazarbayev University.

2019   **Co-Principal investigator:** "Development of a Robotized Vehicle on a KAMAZ Truck Chassis".
- Industrial project funded by the VIST Group company (Russia) (http://vistgroup.ru/en/solutions/robotizirovannaya-tekhnika/) (130,000 USD).

2018 – 2020   **Principal investigator:** "Development of an Intelligent Assistive Robot Manipulation System for Improving the Quality of Life of Disabled People in Kazakhstan" (Project #090118FD5340, 149,310 USD).
- The project proposal was peer-reviewed through ORAU (http://www.orau.org) and funded through the Faculty Development Competitive Research Grant program by Nazarbayev University.

2014 – 2016   **Principal investigator:** "Research of Possible Applications of Renewable Energy for Development of Small/Mobile Autonomous Systems".
- The project was funded through the target funding scheme by the Kazakhstan Ministry of Education and Science (about 200,000 USD).

2012 –2014   **Principal investigator:** "Design and Control of a Gyro Stabilized Pan-Tilt Sensor System with Novel Multiple Object Tracking Algorithms"
- The project proposal was peer-reviewed through ORAU (http://www.orau.org)
- Research project grant from the Kazakhstan Ministry of Education and Science (about 90,000 USD).

2012 – 2013   **Co-Principal investigator (initial stage):** "Enhanced Object Manipulation Using Multigrasp Robotic Hand for Intelligent Industrial Automation"
- The research grant was awarded within the joint Kazakhstan Technology Commercialization Project of the Kazakhstan Ministry of Education and Science and the World Bank

2012 – 2013	**Co-Principal investigator:** "Hybrid Quadruped Robotic Platform for Investigation of Synergistic Legged and Wheeled Locomotion",
	• The research project grant from the Kazakhstan Ministry of Education and Science
2012	**Principal investigator:** "Investigation of Sensor Fusion Algorithms with a Pan-Tilt LIDAR System". Nazarbayev University seed research grant (20,000 USD)
2011	**Co-Principal investigator (Phase 1):** "Study and Development of Renewable Energy and Smart Grid Technologies With Purpose of Potential Application in Kazakhstan"
	• The project was funded by the Kazakhstan Ministry of Education and Science for funding within the 2011 research projects portfolio of NURIS.
2008	**Principal investigator:** "Analysis and Application of Artificial Intelligence Techniques for Modeling and Condition Assessment of Power System Apparatus (on the Example of Power Transformers)"
	• The project was funded by JCS "Science Fund" within the frame of the "Sharyktau" competition (8,000 USD)

AWARDS

2018	**Kazakhstan Scopus Award 2018 - Top Researcher in Engineering and Technologies.** (administered by Elsevier)
2017	**The Certificate of Merit of the Republic of Kazakhstan** A state award for "…achievements in state and public activities, significant contribution to the social-economic and cultural development of the country, strengthening friendship and cooperation among nations"
2005 – 2009	**Kazakhstan Presidential Bolashak Scholarship** (administered by JSC "Center for International Programs", the Kazakhstan Ministry of Education and Science)
2008	**"Sharyktau-2008" competition award** for young Kazakhstan scientists on innovation research in the "Information and Space Technologies" direction (administered by JCS "Science Fund", Astana, Kazakhstan)
2004 – 2006	**Young scientists' Kunaev award for best research works in fundamental sciences** (administered by the Kazakhstan Ministry of Education and Science)

PROFESSIONAL DEVELOPMENT/TRAINING

July –Oct. 2021	Udacity C++ Programming nanodegree program (online);
July – Sept. 2021	Udacity Robotics Software Engineer nanodegree program (online);
Sept. 2017	Summer School on Foundations of Robotics and Autonomous Learning, TU Berlin, Germany
July 2013	Telerobotics Summer School 2013, Keio University, Japan
April 2011	Energy Training Week, International Energy Agency, Paris, France
April 2011	Workshop "The Use of Learning Outcomes in Higher Education" within the TEMPUS project "Chemical Engineering Curriculum Development and International Recognition", Astana, Kazakhstan
Nov. 2010	2nd Science & Technology Training & Education Program for KISTEP-NIF JOINT PROJECT on Foresight Research, Astana

PROFESSIONAL AFFILIATION

2011 – present   IEEE Membership (IEEE Senior Member)
2013 – present   Member of the IEEE Robotics and Automation Society

ACADEMIC SERVICE

Research publication peer-review activity

IEEE Robotics and Automation Letters

IEEE/ASME Transactions on Mechatronics

IEEE Transactions on Industrial Electronics

Robotics and Autonomous Systems

ASME Journal of Mechanical Design

International Journal of Advanced Robotic Systems

Neural Computing and Applications

2020 IEEE 16th International Conference on Automation Science and Engineering (CASE).

2020 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)

2020, 2014, 2016 IEEE/ASME Conference on Mechatronics and Embedded Systems (MESA)

2015, 2014 American Control Conferences

2013, 2014 Kazakhstan National Center of Science and Technology Evaluation, peer-reviewing research grant proposals submitted for funding and annual reports being funded by government.

Organized or chaired sessions
- Chair of the regular session SuBT9 "Mechanism Design" at the 2019 IEEE 15th International Conference on Automation Science and Engineering (CASE), Vancouver, Canada, August 2019
- Chair of the regular session ThAT6 "Kinematics" at the 2014 IEEE/ASME International Conference on Advanced Intelligent Mechatronics, Besançon, France, July 2014

Nazarbayev University (NU), Astana, Kazakhstan (instruction in English):

Dept. of Electrical and Computer Engineering (Acting Chair)
- ❖ Management of the department including dealing with dept. faculty and student-related issues, conducting faculty renewal/promotion evaluation, program course arrangements and scheduling, faculty workload assignment and monitoring, etc.
- ❖ Member of the governing board of the School of Engineering and Digital Sciences (SEDS);
- ❖ Dept. representative in the SEDS Teaching and Learning Committee;
- ❖ Revision and modification of PhD in Electrical Engineering, MSc in Electrical and Computer Engineering and BEng in Electrical and Computer Engineering program curricula;
- ❖ Development of the departmental laboratory infrastructure;
- ❖ Performing short-term duties of an Acting Dean of the School of Engineering and Digital Sciences.
- ❖ Teaching ECE courses:
  - *Programming for Engineers (Fall 2020);*
  - *Undergraduate capstone project supervision (Fall 2020 – onwards),*
  - *Master student thesis supervision (Fall 2020 - onwards)*

Dept. of Robotics and Mechatronics (Assistant/Associate Professor):
- ❖ One out of three founding faculty members of the dept. who were setting up BSc in Robotics and Mechatronics (R&M) program and robotics research program at Nazarbayev University;
- ❖ Assisting in developing MSc in Robotics program;
- ❖ Development course contents and teaching the following Computer Science and/or Robotics &Mechatronics master/PhD level courses:

- *Industrial Robotics (Fall 2019, 2018, 2017, 2016);*
- *Hardware/Software Co-Design (Spring 2021, 2020, 2019, 2018, 2017, 2016);*
- *Master projects supervision (Fall 2020, Spring 2020, 2019, 2017, Fall 2016);*
- *PhD student supervision (2017 – present)*

- ❖ Development course contents and teaching the following R&M undergraduate courses:
  - *Embedded Systems (Fall 2019, 2018, 2017, 2016, 2015, 2014, 2013);*
  - *Microcontrollers with Lab (Spring 2019, 2015, 2013, 2014);*
  - *Robotic/Mechatronic System Design (Spring 2018, 2017, 2016, 2015);*
  - *Graduate projects supervision (Spring 2020, 2019, 2018, 2017, 2016, 2015);*
  - *Signals and Sensing with Lab (Fall 2014);*
  - *Electric and Electronic Circuits II with Lab (Lab sessions, Spring 2013,2014);*
  - *Computer Aided Drawing (Fall 2012, Summer 2012);*
  - *Introduction to Robotics and Mechatronics (Fall 2012, 2011);*
  - *Programming to Robotics and Physics (Lab sessions, Spring 2012);*
  - *Freshman Robotics Colloquium (Spring 2012);*
- ❖ Development high school course "Fundamentals of Robotics" and training high school teachers for Nazarbayev Intellectual Schools (www.nis.edu.kz) *(Summer 2012);*
- ❖ Academic advising of undergraduate Robotics and Mechatronics and graduate Robotics students;
- ❖ Tutoring students on individual basis during office hours;
- ❖ Supervising PhD, master and undergraduate student research and graduation projects (Spring 2015 – present).
- ❖ Representative of the R&M Department in/during:
  - *School Research Committee (2018 - 2019)*
  - *School Teaching and Learning Committee (2015 – 2018)*
  - *School Library Committee (2011 – 2012);*
  - *School Website Development Committee (2013 – 2014);*
  - *Member of various tender commissions for procurement of teaching and research equipment (2011- present);*
  - *Presentation of the R&M laboratories and projects during VIP guest visits to NU including visits of President of the Republic of Kazakhstan N. Nazarbayev (2018, 2012), Prime Minister of the Russian Federation D. Medvedev (2013), groups of top Kazakhstan government officials (2019, 2018, 2012, 2013), senior Kazakhstan army officers (2013), guest international academics, high school and college students etc.*
- ❖ Service within the R&M Department:
  - *Member of Departmental Curriculum Committee (2011- 2020);*
  - *Member of Departmental Recruitment Committee (2011- present);*
  - *Education/research equipment and consumables selection and procurement facilitating (2011- present) including work on compiling and translating tender technical specification and documentation to Russian language;*
  - *Facilitating visits to the department and presentation of research projects to NU visitors (2011-present);*
  - *Facilitating visits to the department of and delivering introductory talks to Nazarbayev Intellectual School students (2011-present);*
  - *Organizing and supervising field trip visits for Robotics students to local industrial enterprises (2012-2013);*
  - *Assisting senior faculty members in research and organization work;*
  - *Responding to various requests from the School and the University administration.*

External service activities (in English and Russian)

❖ Representative of Nazarbayev University in:
- *Annual Forums of the Association of the Kazakhstan Manufacturing Industry (2017, 2019)*
- *Round tables on Kazakhstan Industry 4.0 program development (2017)*
- *Working tables of Smart Astana concept development (2017)*
- *Supervisory Board of NURIS (2016 – present)*
- *External member of the PhD dissertation council at the Faculty of Information Technologies, the L. Gumilyov Eurasian National University (2020, 2019, 2015)*
- *External member of the PhD dissertation council at the Faculty of Power Engineering, S. Toraighyrov Pavlodar State University (2016)*
- *Chair of the State Examination Committee for «Computer Engineering» bachelor program's state exams and graduation project evaluations at Eurasian National University (2015)*
- *Chair of the State Examination Committee for «Radiotechnics, Electronics and Telecommunications» master program's state exams and thesis project evaluation at S. Seifullin Kazakh Agro-Technical University (2016-2017)*
- *NU Equipment Committee (2014-2016);*
- *The University Senate (2012-2013 academic year);*
- *The University Academic Council (nominated by the University Senate as the SST faculty representative in the AC for 2012-2013 academic year);*

At the University of Liverpool, U.K.:

❖ Assistance and co-supervision of undergraduate students during computer and electrical laboratory sessions:
- *Introduction to Java programming;*
- *Electronic and Electric Circuit Design;*
- *Electric Machines; Feedback Control Systems;*
- *Power Transmission Systems;*
- *Year 1 and 2 course projects.*

At Pavlodar State University, Kazakhstan (in Russian):

❖ Development course contents and teaching the following undergraduate courses:
- *Control Systems of Electric Drives;*
- *Electric Power Systems;*
- *Computer Modeling in Electrical Engineering;*
- *Fundamentals of Microprocessor Systems;*
❖ Assisting undergraduate and postgraduate students in course, final and research projects.

ADMINISTRATIVE EXPERIENCE

At Nazarbayev University (NU), Astana, Kazakhstan in 2009 – 2010 (English and Russian):

❖ Project management on establishing Nazarbayev University, including projects of establishing the Center for Energy Research (CER) (currently – Nazarbayev University Research and Innovation System (NURIS)) and the School of Engineering (first development phase) at NU.
❖ Establishment of physics, chemistry and biology teaching laboratories as part of the new Foundation Program in cooperation with University College London, U.K.
❖ Business negotiation and correspondence with international universities (Lawrence Berkeley National Laboratory (LBNL) at UC Berkeley, USA, and University College London, U.K.), organizations and industry – partners of NU for establishing CER and NU School of Engineering, preparation of strategic, analytical, budget and legal documentation, etc.

- ❖ Other technical projects coordination, participation and representing NU at conferences and seminars on renewable energy policy, ministry working groups on draft legislation development, international cooperation in power engineering, etc.
- ❖ Other technical projects coordination, including a project of establishing a 1 MW solar station in the NU campus sponsored by the Government of Japan within the "Cool Earth" programme grant.

REFERENCES

Professor Vassilios Tourassis
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LIST OF PUBLICATIONS

Google Scholar citation report of research publications
http://scholar.google.com/citations?user=D7WWMgEAAAAJ&hl=ru&oi=ao

❖ PEER-REVIEWED JOURNALS

1. I. Tursynbek and **A. Shintemirov**, Infinite Rotational Motion Generation and Analysis of a Spherical Parallel Manipulator with Coaxial Input Axes, *Mechatronics,* vol. 78: 102625*,* 2021.

2. A. Oleinikov, S. Kusdavletov, **A. Shintemirov**, and M. Rubagotti, Safety-Aware Nonlinear Model Predictive Control for Physical Human-Robot Interaction, *IEEE Robotics and Automation Letters,* 2021, vol. 6(3): 5665 – 5672, 2021

3. **A. Shintemirov,** T. Taunyazov, B. Omarali, A. Kim, A. Nurbayeva, A. Bukeyev**,** M. Rubagotti, An Open-Source 7-DOF Wireless Human Arm Motion Tracking System for Use in Robotics Research, *Sensors (MDPI*), 20(11), 3082, 2020

4. S. Soltan, A. Oleinikov, M. F. Demirci and **A. Shintemirov**, Deep Learning-Based Object Classification and Position Estimation Pipeline for Potential Use in Robotized Pick-and-Place Operations, *Robotics (MDPI),* 9(3), 63, 2020

5. M. Rubagotti, T. Taunyazov, B. Omarali and **A. Shintemirov**, Semi-Autonomous Robot Teleoperation with Obstacle Avoidance via Model Predictive Control, *IEEE Robotics and Automation Letters*, vol. 4(3): 2746 – 2753, 2019

6. Y. Raziyev, R. Garifulin, **A. Shintemirov**, T.D. Do, Development of a Power Assist Lifting Device with a Fuzzy PID Speed Regulator, *IEEE Access,* vol. 7: 30724 – 30731, 2019

7. T. Taunyazov, M. Rubagotti and **A. Shintemirov**, Constrained Orientation Control of a Spherical Parallel Manipulator via Online Convex Optimization, *IEEE/ASME Transactions on Mechatronics*, Vol. 23 (1): 252-261, 2018

8. A. Khakimova, A. Kusatayeva, A. Shamshimova, D. Sharipova, A. Bemporad, Y. Familiant, **A. Shintemirov**, V. Ten, M. Rubagotti, Optimal Energy Management of a Small-Size Building via Hybrid Model Predictive Control, *Energy and Buildings,* vol. 140: 1 – 8, 2017

9. **A. Shintemirov,** A. Niyetkaliyev, M. Rubagotti, Numerical Optimal Control of a Spherical Parallel Manipulator Based on Unique Kinematic Solutions*, IEEE/ASME Transactions on Mechatronics*, Vol 21 (1): 98-109, 2016

10. K. Telegenov, Y. Tlegenov, S. Hussain and **A. Shintemirov,** Preliminary Design and Analysis of a Three Finger Underactuated Adaptive End Effector with a Breakaway Clutch Mechanism, *Journal of Robotics and Mechatronics,* vol. 27(5): 496 – 503, 2015

11. K. Telegenov, Y. Tlegenov and **A. Shintemirov,** A Low-Cost Open-Source 3-D Printed Three-Finger Gripper Platform for Research and Educational Purposes, *IEEE Access*, vol. 3: 638 – 647, 2015

12. **A. Shintemirov,** Mathematical Morphology Based Reference Signals Generation for Active Power Filters, *Electronics Letters*, IET, 2013, vol. 49 (10), May 2013

13. **A. Shintemirov**, W.H. Tang, Q.H. Wu, Transformer Core Parameter Identification Using Frequency Response Analysis, *IEEE Transactions on Magnetics*, vol. 46 (1): 141-149, 2010

14. **A. Shintemirov**, W.H. Tang, Q.H. Wu, Transformer Winding Condition Assessment Using Frequency Response Analysis and Evidential Reasoning, *IET Electric Power Application,* vol. 4(3): 198 – 212, 2010

15. **A. Shintemirov**, W.J. Tang, W.H. Tang, Q.H. Wu, Improved Modeling of Power Transformer Winding Using Bacterial Swarming Algorithm and Frequency Response Analysis, *Electric Power Systems Research*, Elsevier, vol 80 (9): 1111-1120, 2010

16. **A. Shintemirov**, W.H. Tang, Q.H. Wu, A Hybrid Winding Model of Disc-Type Power Transformers for Frequency Response Analysis, *IEEE Transactions on Power Delivery*, vol. 24 (2): 730 – 739, 2009

17. **A. Shintemirov**, W.H. Tang, Q.H. Wu, Power Transformer Fault Classification Based on Dissolved Gas Analysis by Implementing Bootstrap and Genetic Programming, *IEEE Transactions on Systems, Man, and Cybernetics-Part C*, vol. 39 (1): 69 – 79, 2009

18. Z. Yang, W.H. Tang, **A. Shintemirov**, Q.H. Wu, An Association Rule Mining-based Dissolved Gas Analysis for Fault Classification of Power Transformers, *IEEE Transactions on Systems, Man, and Cybernetics-Part C*, vol. 39 (6):597 – 610, 2009

❖ **PEER-REVIEWED CONFERENCE PAPERS**

1. A. Nurpeissova, T. Tursynbekov and **A. Shintemirov**, An Open-Source Mechanical Design of ALARIS Hand: A 6-DOF Anthropomorphic Robotic Hand, *2021 IEEE International Conference on Robotics and Automation (IEEE ICRA 2021),* China, 2021.

2. S. Abilkassov, A. Nurlybayev, S. Soltan, A. Kim, N. Yesmagambet, E. Shpieva, Z. Yessenbayev and **A. Shintemirov**, Facilitating Autonomous Vehicle Research and Development Using Robot Simulators on the Example of a KAMAZ NEO Truck, *The 23rd IEEE International Conference on Intelligent Transportation Systems (IEEE ITSC 2020)*, Greece, 2020

3. A. Sarsenov, A. Yessenbayeva, **A. Shintemirov**, A. Yazici, Detection of Objects and Trajectories in Real-time using Deep Learning by a Controlled Robot, *The International Conference on Robotics, Computer Vision and Intelligent Systems (ROBOVIS)*, vol. 1, p. 131-140, 2020

4. I. Tursynbek and **A. Shintemirov**, Infinite Torsional Motion Generation of a Spherical Parallel Manipulator with Coaxial Input Axes, *IEEE/ASME International Conference on Advanced Intelligent Mechatronics (IEEE/ASME AIM 2020),* USA, 2020

5. I. Tursynbek and **A. Shintemirov**, Modeling and Simulation of Spherical Parallel Manipulators in CoppeliaSim (V-REP) Robot Simulator Software, *The International Conference "Nonlinearity, Information and Robotics"*, Russia, 2020

6. S. Rakhimkul, A. Kim, A. Pazylbekov and **A. Shintemirov**, Autonomous Object Detection and Grasping Using Deep Learning for Design of an Intelligent Assistive Robot Manipulation System, *IEEE International Conference on Systems, Man and Cybernetics (IEEE SMC2019)*, Italy, 2019

7. M. Rubagotti, T. Taunyazov, B. Omarali and **A. Shintemirov**, Semi-Autonomous Robot Teleoperation with Obstacle Avoidance via Model Predictive Control, *Robotics: Science and Systems (RSS2019)*, Germany, 2019

8. A. Oleinikov, B. Abibullaev, **A. Shintemirov**, M. Folgheraiter, Feature Extraction and Real-Time Recognition of Hand Motion Intentions from EMGs via Artificial Neural Networks, *The 6th International Winter Conference on Brain-Computer Interface (BRAIN)*, South Korea, 2018.

9. B. Omarali, T. Taunyazov, A. Bukeyev and **A. Shintemirov**, Real-Time Predictive Control of an UR5 Robotic Arm Through Human Upper Limb Motion Tracking, *The 2017 ACM/IEEE International Conference on Human-Robot Interaction (HRI2017)*, Austria, 2017.

10. D. Nurseitov, A. Serekov, **A. Shintemirov**, B. Abibullaev, Design and Evaluation of a P300-ERP based BCI System for Real-Time Control of a Mobile Robot, *The 5th International Winter Conference on Brain-Computer Interface*, South Korea, 2017.

11. **A. Shintemirov**, B. Omarali, F. Muratov, M. Issa, Sh. Salakchinov, T. Alizadeh, Y. Familiant, A Sensorless MPPT-based Solar Tracking Control Approach for Mobile Autonomous Systems, *42nd IEEE Industrial Electronics Conference (IEEE IECON2016)*, Italy, 2016.

12. T. Taunyazov, B. Omarali and **A. Shintemirov**, A Novel Low Cost 4-DOF Wireless Human Arm Motion Tracker System, *6th IEEE RAS&EMBC International Conference on Biomedical Robotics and Biomechatronics (BioRob2016),* Singapore, 2016.

13. N. Omarkulov, K. Telegenov, M. Zeinullin, I. Tursynbek and **A. Shintemirov**, Preliminary Mechanical Design of NU-Wrist: a 3-DOF Self-Aligning Wrist Rehabilitation Robot, 6t*h IEEE RAS & EMBC International Conference on Biomedical Robotics and Biomechatronics (BioRob2016),* Singapore, 2016.

14. B. Omarali, T. Taunyazov, A. Nyetkaliyev and **A. Shintemirov**, System Integration of a Solar Sensor and a Spherical Parallel Manipulator for a 3-Axis Solar Tracker Platform Design, *2015 IEEE/SICE International Symposium on System Integration,* Nagoya, Japan, 2015.

15. N. Omarkulov, K. Telegenov, M. Zeinullin and **A. Shintemirov**, Underactuated Anthropomorphic Finger Design and Analysis for Hand Prosthetics, 37th *Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBS)*, Milano, Italy, 2015.

16. A. Khakimova, A. Shamshimova, D. Sharipova, A. Kusatayeva, V. Ten, A. Bemporad, Y. Familiant, **A. Shintemirov**, M. Rubagotti, Modeling and Hybrid Model Predictive Control of a Smart House, *2015 IEEE 15th International Conference on Environment and Electrical Engineering (EEEIC),* Rome. Italy, 2015.

17. A. Niyetkaliyev and **A.Shintemirov,** An Approach for Obtaining Unique Kinematic Solutions of a Spherical Parallel Manipulator, *The IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM2014)* , Besancon, France, July 2014.

18. Y. Tlegenov, K. Telegenov and **A. Shintemirov,** An Open Source 3D Printed Underactuated Robotic Gripper, *The 10th IEEE/ASME International Conference on Mechatronic and Embedded Systems and Applications (MESA'14)*, Senigallia, Italy, September 2014.

19. A. Begalinova and **A. Shintemirov**, Design of Embedded Gesture Recognition System for Robotic Applications, *2014 IEEE 8th International Conference on Application of Information and Communication Technologies (AICT2014),* Astana, Kazakhstan, 2014.

20. K. Telegenov, Y. Tlegenov and **A. Shintemirov,** An Underactuated Adaptive 3D Printed Robotic Gripper, *10th France – Japan Congress,8th Europe – Asia Congress on Mecatronics*, Japan, November, 2014.

21. Y. Ponomarenko, B. Aubakir, Sh. Hussain and **A. Shintemirov,** An End-Effector Based Upper-Limb Rehabilitation Robot: Preliminary Mechanism Design, *10th France – Japan Congress,8th Europe – Asia Congress on Mecatronics*, Japan, November, 2014.

22. Zh. Kappassov, Y. Khassanov, A. Saudabayev, **A. Shintemirov**, H.A. Varol, Semi-Anthropomorphic 3D Printed Multigrasp Hand for Industrial and Service Robots, *The IEEE International Conference on Mechatronics and Automation (ICMA2013),* Takamatsu, Kagawa, Japan, August 2013.

23. A. Saudabayev, Y. Khassanov, **A. Shintemirov**, H.A. Varol, An Intelligent Object Manipulation Framework for Industrial Tasks, *The IEEE International Conference on Mechatronics and Automation (ICMA2013),* Takamatsu, Kagawa, Japan, August 2013.

24. **A. Shintemirov,** Reference Signals Generation for Active Power Filter Compensation Using Mathematical Morphology. *2013 Fourth International Conference on Power Engineering, Energy and Electrical Drives (POWERENG),* Istanbul, Turkey, May 2013.

25. **A. Shintemirov,** Modeling of Power Transformer Winding Faults for Interpretation of Frequency Response Analysis (FRA) Measurements. *2013 Fourth International Conference on Power Engineering, Energy and Electrical Drives (POWERENG),* Istanbul, Turkey, May 2013.

26. W.H Tang, **A. Shintemirov,** Q.H. Wu**,** Detection of Minor Winding Deformation Fault in High Frequency Range for Power Transformer, in: *Proceedings of the 2010 IEEE Power & Energy Society General Meeting,* 2010, 6 c.

27. **A. Shintemirov**, W.H. Tang, Q.H. Wu, Construction of Transformer Core Model for Frequency Response Analysis with Genetic Algorithm, in: *Proceedings of the 2009 IEEE Power & Energy Society General Meeting,* Calgary, Alberta, Canada, 2009, 5 p.

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