

# Brain Actuated Wheelchair Using Neural Signals as an Assistive Home Technology

Abzal Serekov  
Damir Nurseitov

Supervisor: Berdakh Abibullaev  
Co-supervisor: Almas Shintemirov

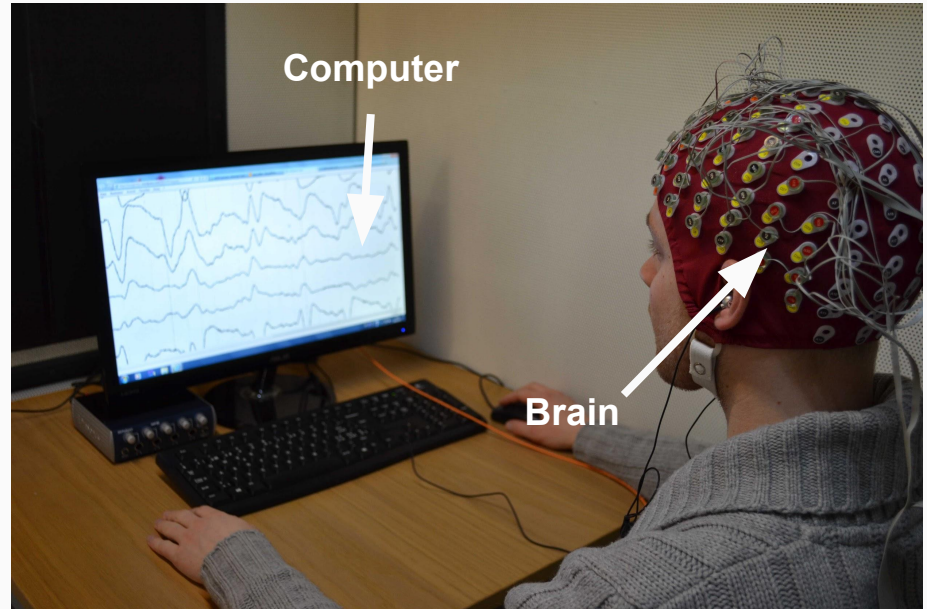
Helping Student: Artemiy Oleinikov



# What is **BCI**? (**B**rain **C**omputer **I**nterface)

- Invasive
- Noninvasive
  - EEG
  - MEG
  - ECoG

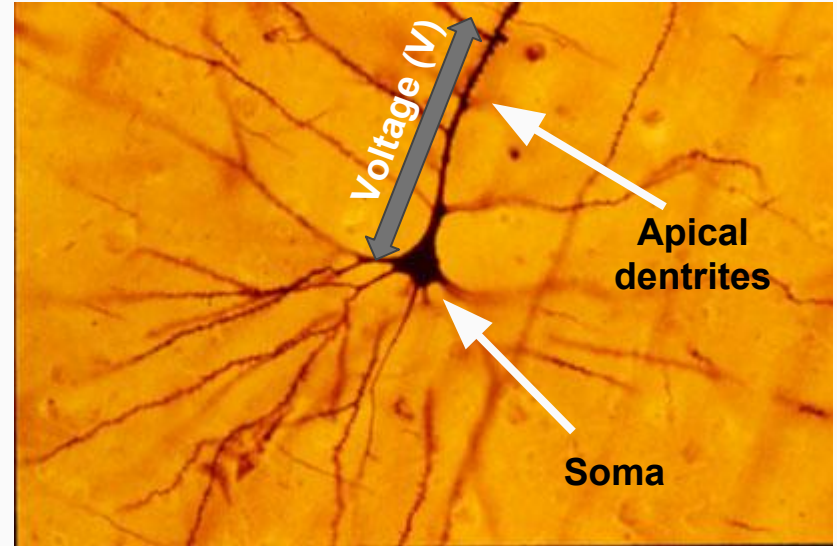
**EEG** (**E**lectro**E**ncephalo**G**raphy) is a medical imaging technique that reads scalp electrical activity generated by brain structures.



BCI example (EEG)

# How signal is generated?

Signals are differences of electrical potentials between **soma** (body of neuron) and **apical dendrites** (neural branches).

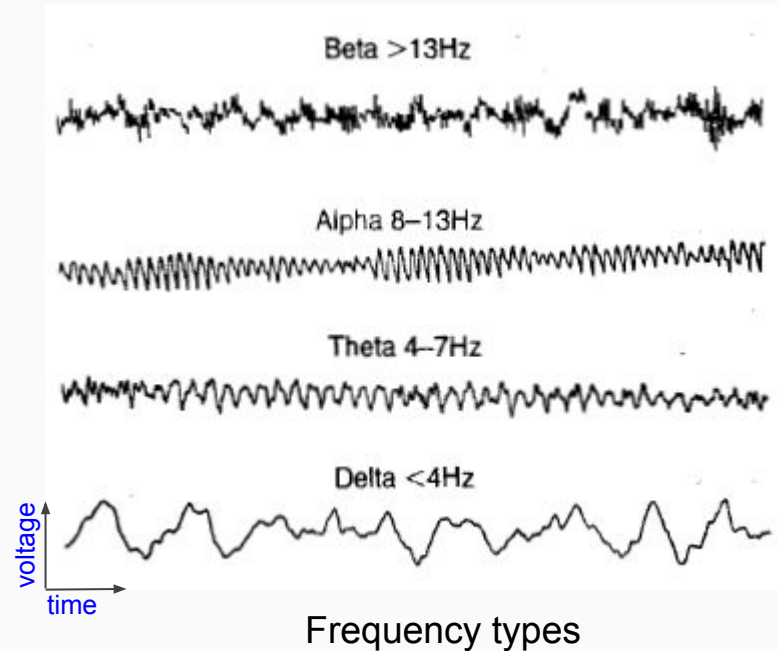


Neural Cell

# Frequency bands

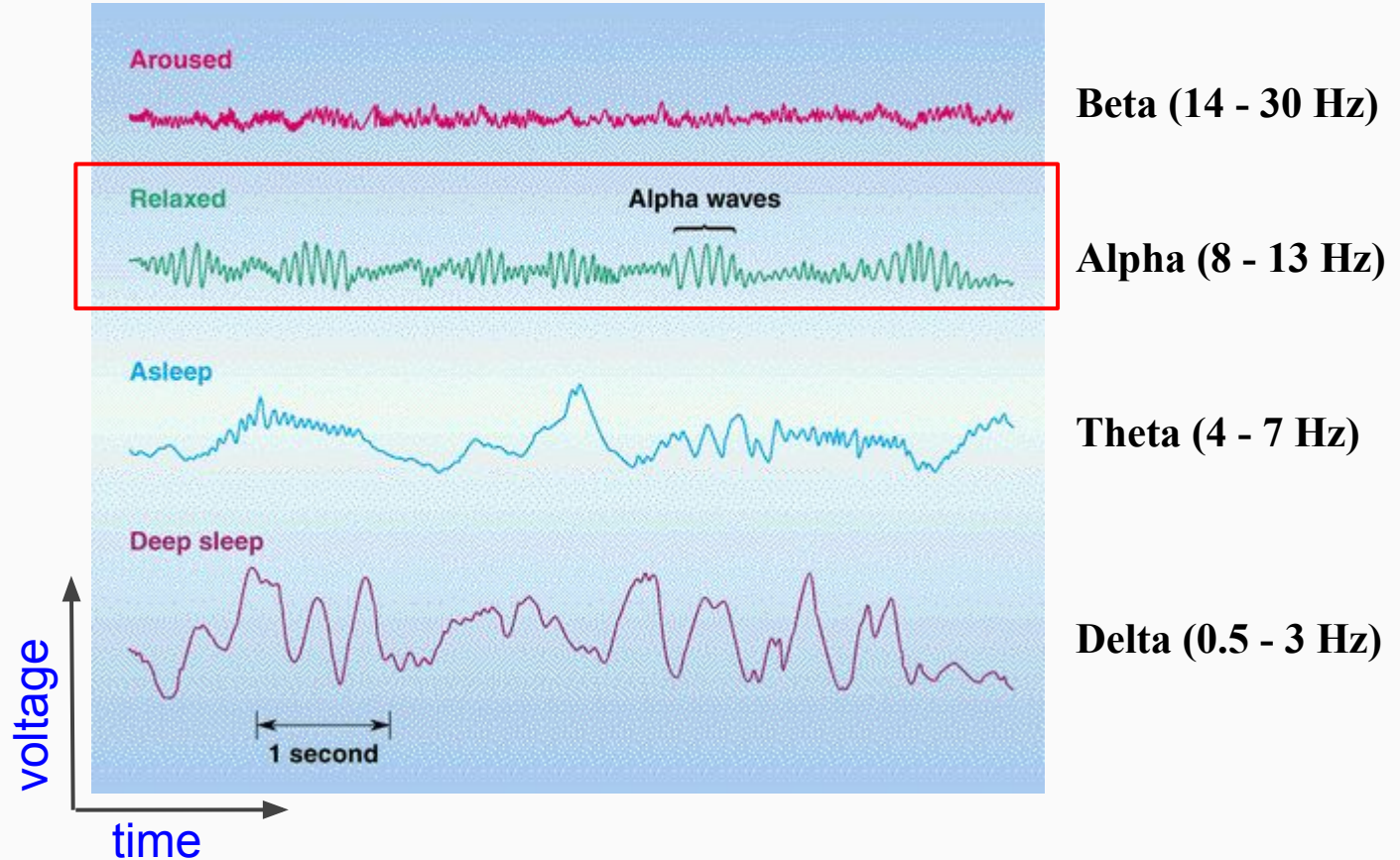
The most important frequencies from the physiological viewpoint lie in the range of 0.1 to 30 Hz.

- Delta ( $\delta$ ):  $0.5 \leq f < 4$  Hz;
- Theta ( $\theta$ ):  $4 \leq f < 8$  Hz;
- **Alpha ( $\alpha$ ):  $8 \leq f \leq 13$  Hz;**
- Beta ( $\beta$ ):  $f > 13$  Hz.

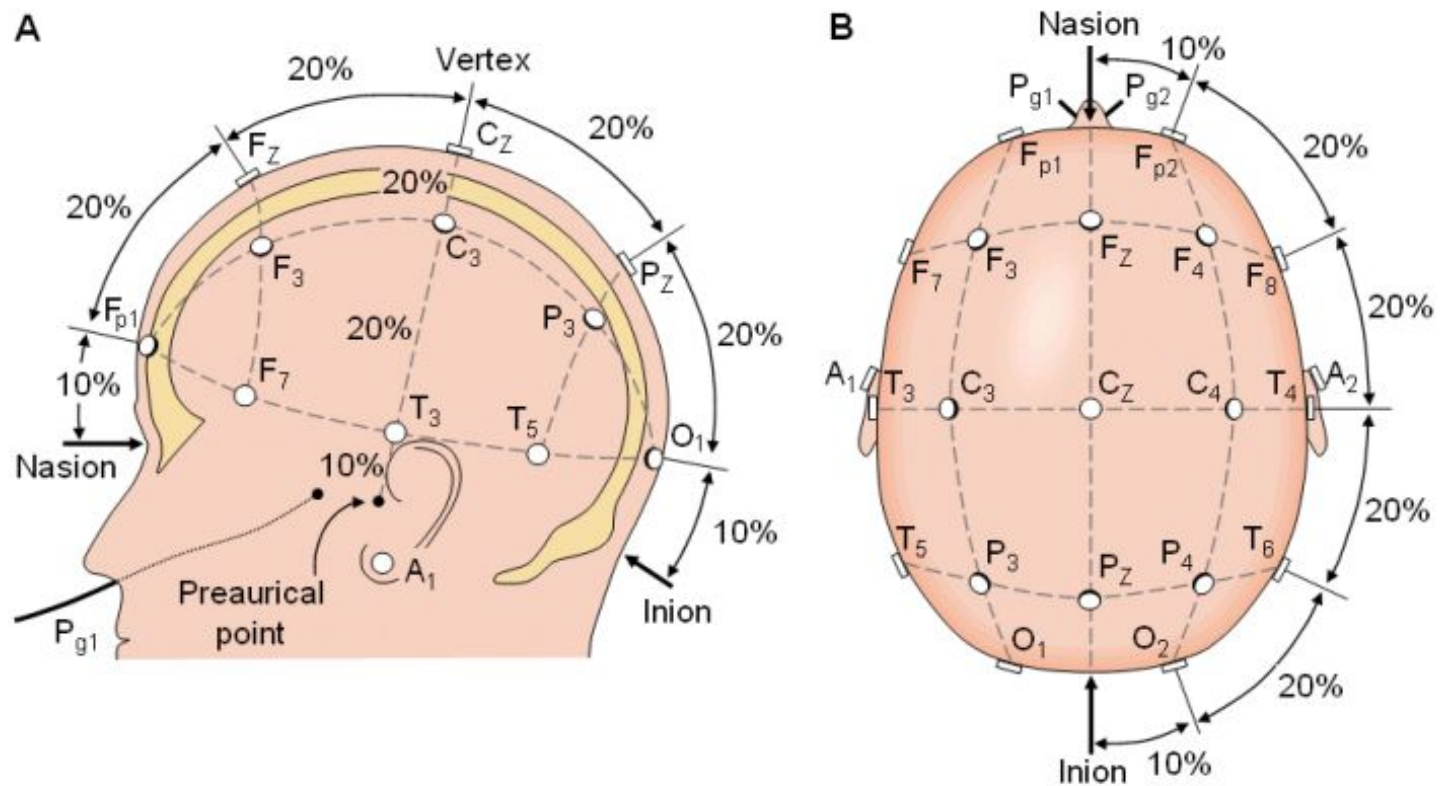


# Frequency type characteristics

We are mostly interested in neural oscillations in the frequency range of 8-13 Hz, which are also known as **Alpha** waves.



# Internationally standardized 10-20 System



**Figure 2.** The international 10-20 system seen from (A) left and (B) above the head. A = Ear lobe, C = central, Pg = nasopharyngeal, P = parietal, F = frontal, Fp = frontal polar, O = occipital.



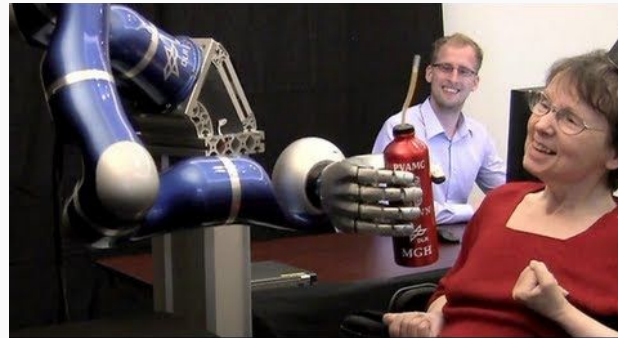
# BCI applications



BCI Speller



BCI Game Control



BCI Robotic Arm Control

# Wheelchair Control with BCI



Tanaka et al. 2005



# Wheelchair Control with BCI (Specifications)

- Robot Jaguar instead of real wheelchair
- Visual Interface -- video from robot camera
- Simple Commands: **Go, Left, Right, Back.**

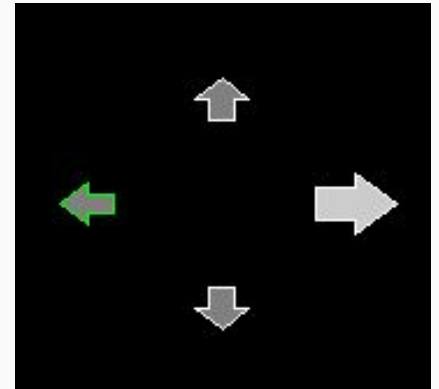
# Technologies used

- Emotiv Epoc BCI
- Jaguar 4x4 Wheel Robot
- buffer\_bci framework



# ERP (Event Related Potential)

- **ERP** -- synchronous (**external stimuli**)
- ERSP -- asynchronous (imagination)
- Location of response depends on modality of stimulus: **visual**, tactile, auditory
- P300 -- visual stimuli (arrow flashes)



Visual stimuli

# Artifacts (Noise)

- Bad channels
- Slow electrode drifts
- Eye movement/blinks
- Muscle movement
- Relaxation (deep breath) / stressed
- Very subject and session related

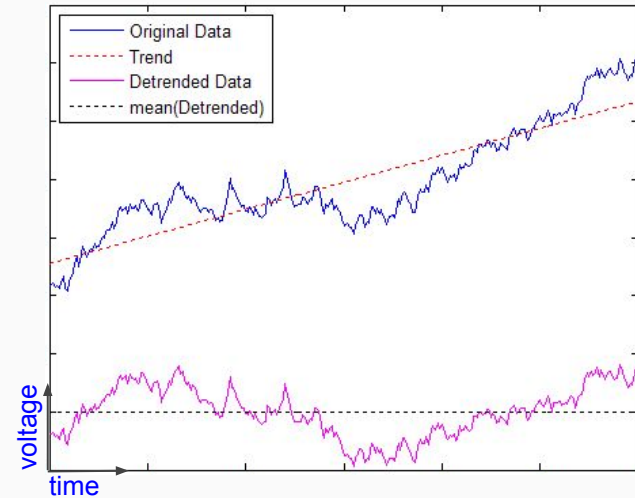
# Remove artifacts → Signal Processing

- Detrending
- Bad-channel identify and remove
- Re-referencing/Spatial Filtering
- Spectral filtering
- Bad-trial ID & remove
- Classifier Training

# Detrending

**Problem:** Slow drifts and trends mess the signal

**Solution:** Compute best-fit line and subtract from the signal

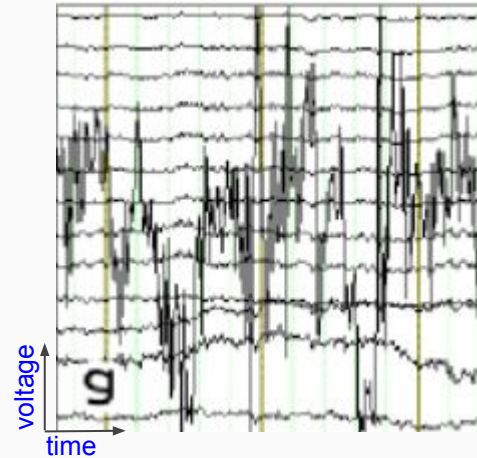




# Bad channel identify and remove

**Problem:** Some channels doesn't work and create only noise

**Solution:** Identify channels with excessively high power and remove them



Bad channel example

# Spatial Filter

**Problem:** Common noise (e.g. noisy/cold place) affects all channels which mess signals

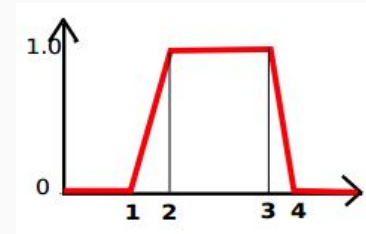
**Solution:**

- **CAR** (*Common Average Reference*). Remove average signal from all channels
- **SLAP** (*Surface Laplacian*). Remove channel correlation and local average signal

# ERP Spectrally Filter

**Problem:** We are only interested in a given frequency range

**Solution:** Apply a spectral filter to remove frequencies outside the range of interest



Spectral filter

# Bad trial identify and remove

**Problem:** Noise after eye blink and other artifacts cause mistakes in signal which results in bad classifier

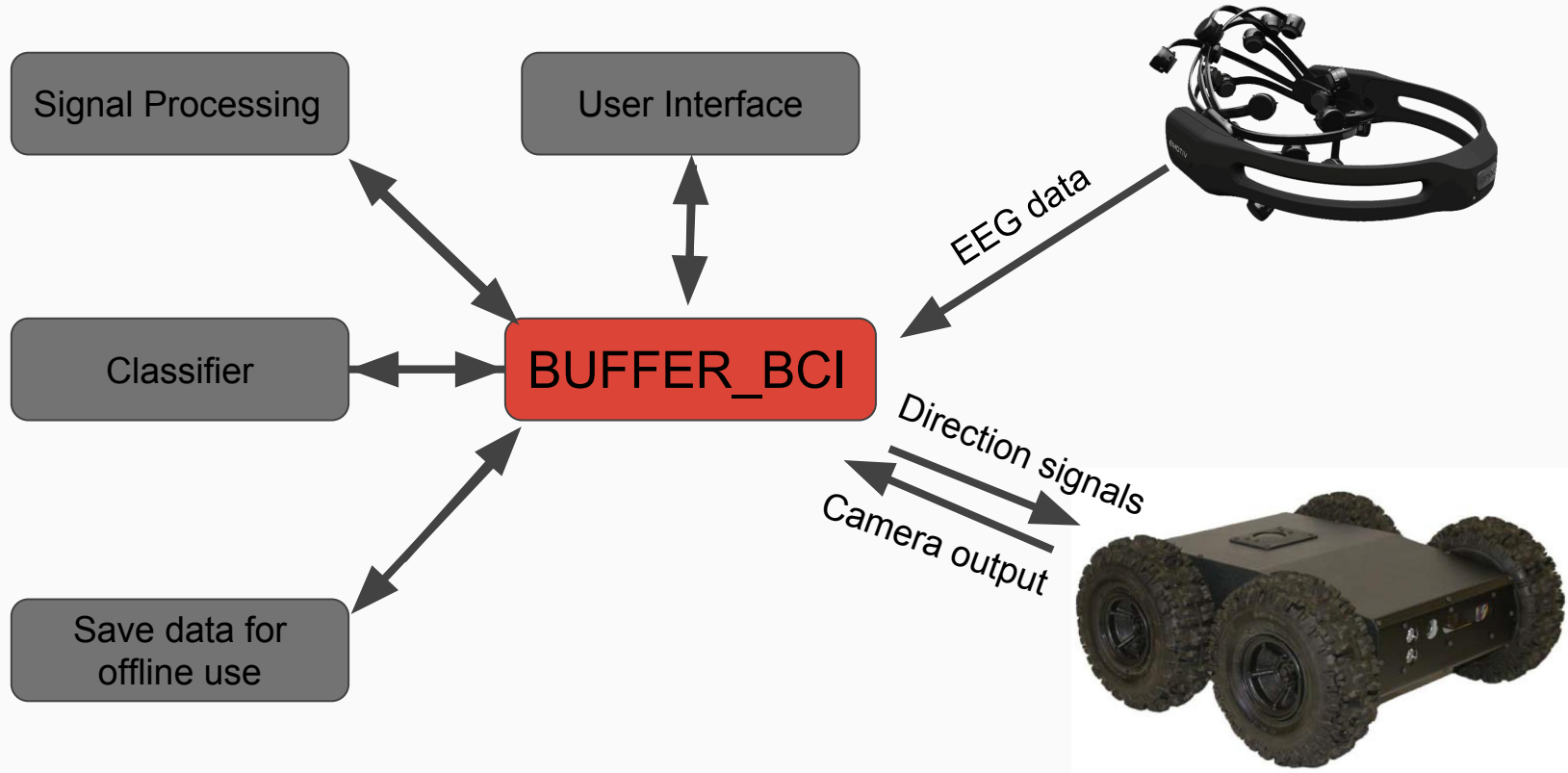
**Solution:** Identify excessively high power signals and remove them

# Train classifier

**Problem:** We need a classifier model to predict user intention with high accuracy

**Solution:** Use regularized logistic regression on training data

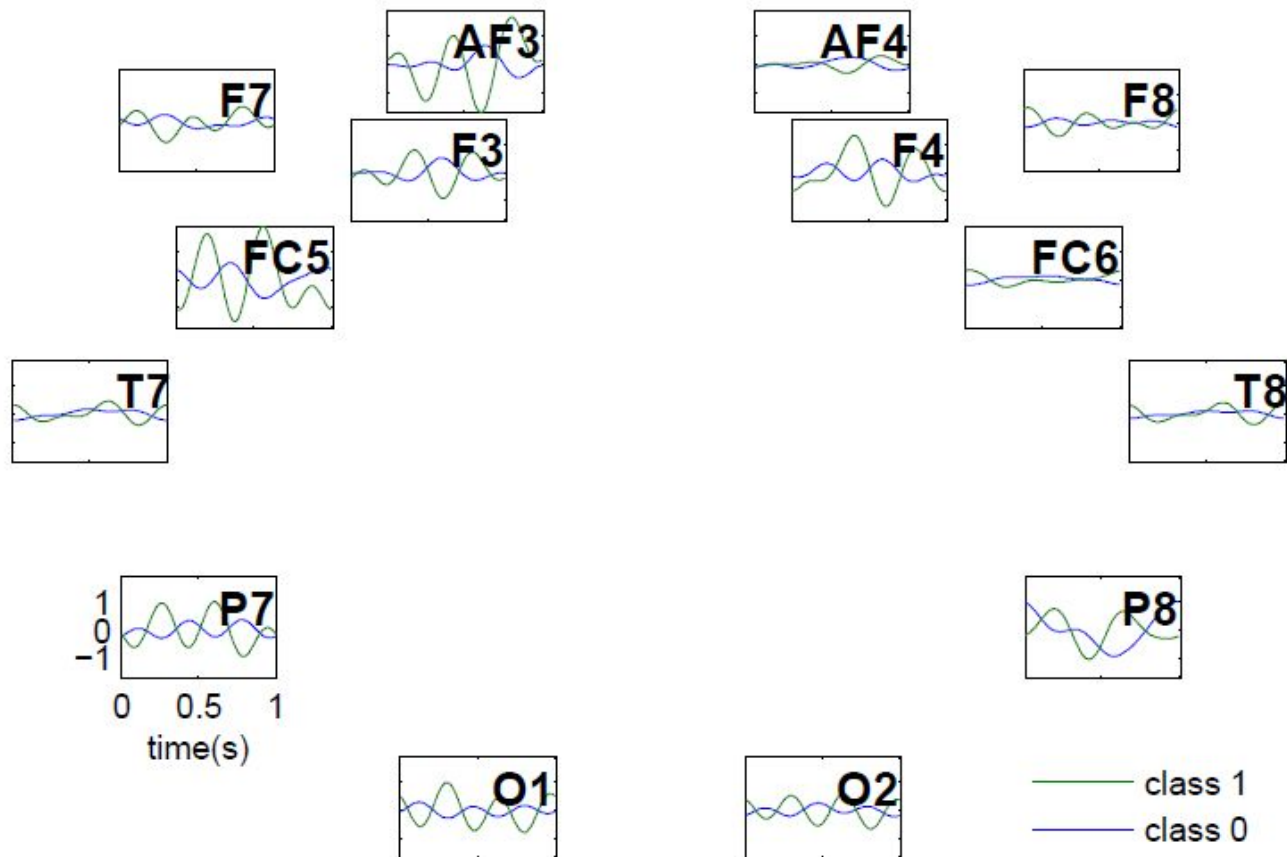
# System Architecture





Video demo

# Results (ERP data)



# Results

- Final testing. 5 persons tested our system.

Subject	1	2	3	4	5
Successful movements	7/16	6/16	7/16	8/16	9/16

Offline classification validation (average): 54.2% (from training data)

Practical classification rate: 46.25% (testing)

# Limitations

- Bad accuracy and inconsistency of signal
- Lack of conductive gel (we used saline solution)
- Sensor arrangement (Not designed to read EEG from central and parietal lobes)
- Different main application of Emotiv Epoc
- Time constraints and problems regarding user's concentration

# Potential Future Work

As a future work we can:

- Try other BCIs, which could meet the requirements of our system better than Emotiv Epoc
- Improve interface and try to combine P300 with SSVEP or MI
- Collect data from disabled people and see if our system is applicable to them

# References

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Thanks